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Interfacing of Servo motor SG90

Servo Motor

A **Servo motor** is an electrical device which can push or rotate an object with great precision. If you want to rotate and object at some specific angles or distance, then you use **Servo motor**. It is just made up of simple **motor** which run through **servo** mechanism.

It consists of three parts:

1. Controlled device
2. Output sensor
3. Feedback system

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Working principle of Servo motor

1. A Servo consists of a Motor (DC or AC), a potentiometer, gear assembly and a controlling circuit.
2. First of all we use gear assembly to reduce RPM and to increase torque of motor.
3. Say at initial position of servo motor shaft, the position of the potentiometer knob is such that there is no electrical signal generated at the output port of the potentiometer.
4. Now an electrical signal is given to another input terminal of the error detector amplifier.
5. Now difference between these two signals, one comes from potentiometer and another comes from other source.

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Working principle of Servo motor

6. It will be processed in feedback mechanism and output will be provided in term of error signal.
7. This error signal acts as the input for motor and motor starts rotating.
8. Now motor shaft is connected with potentiometer and as motor rotates so the potentiometer and it will generate a signal.
9. So as the potentiometer's angular position changes, its output feedback signal changes. After sometime the position of potentiometer reaches at a position that the output of potentiometer is same as external signal provided.

Components Required

- Arduino Mega
- Servo Motor
- Jumper wires

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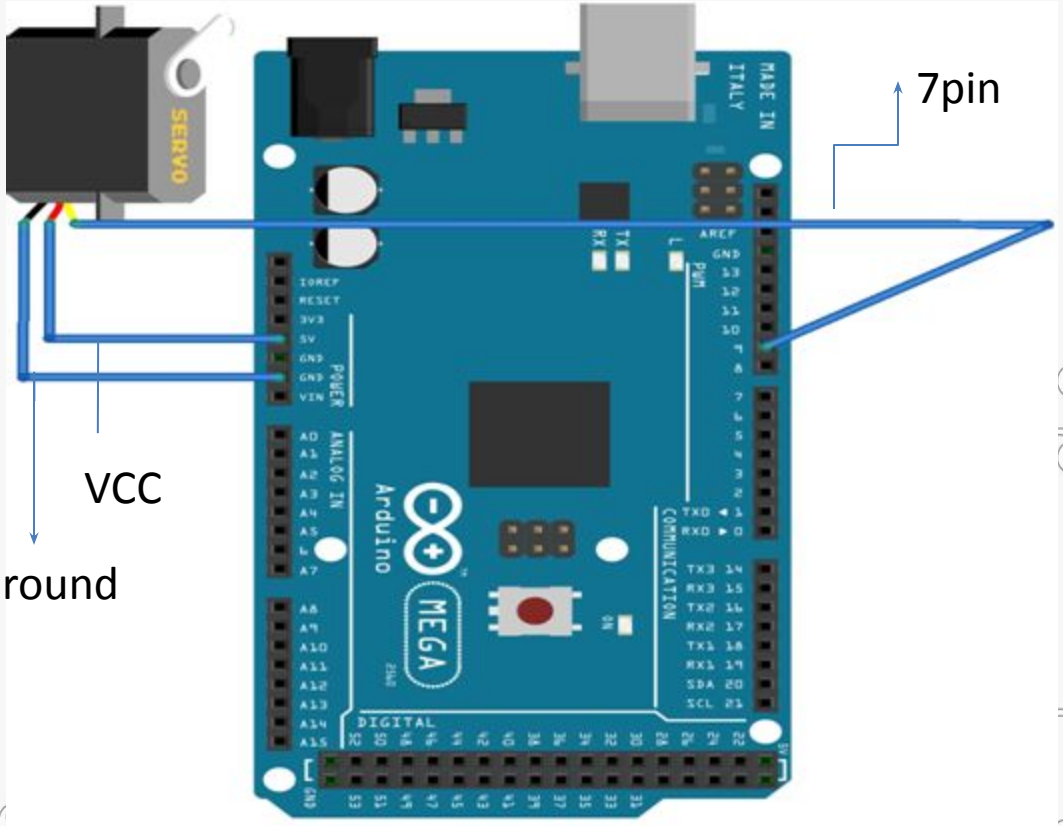
Connection Diagram



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Connections

1. Connect Red wire of servo with VCC(+5V) of Arduino.
2. Connect Black wire of servo with GND of Arduino.
3. Connect orange wire of servo with 9 pin Arduino.

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Code

interfacing_of_servo_motor | Arduino 1.8.19

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interfacing_of_servo_motor

```
*/

#include <Servo.h>

Servo myservo;  // create servo object to control a servo
// twelve servo objects can be created on most boards

int pos = 0;    // variable to store the servo position

void setup() {
  myservo.attach(9);  // attaches the servo on pin 9 to the servo object
}

void loop() {
  for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180 degrees
    // in steps of 1 degree
    myservo.write(pos);              // tell servo to go to position in variable 'pos'
    delay(15);                       // waits 15ms for the servo to reach the position
  }
  for (pos = 180; pos >= 0; pos -= 1) { // goes from 180 degrees to 0 degrees
    myservo.write(pos);              // tell servo to go to position in variable 'pos'
    delay(15);                       // waits 15ms for the servo to reach the position
  }
}
```

1 Arduino Uno on COM6

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Project Link : https://youtu.be/c-E_ZuoaPYE